469

MOTOR PROTECTION SYSTEM

Complete integrated protection and management of medium and large motors

KEY BENEFITS

• Comprehensive motor protection plus voltage dependant overload curves, torque metering and protection, broken rotor bar protection
• Most advanced thermal model - Including multiple RTD inputs for stator thermal protection
• Minimize replacement time - Draw-out construction
• Complete asset monitoring - Temperature, Analog I/O, full metering including demand & energy
• Improve uptime of auxiliary equipment - Through I/O monitoring
• Reduce troubleshooting time and maintenance costs - Event reports, waveform capture, data logger
• Built in simulation functions simplify testing and commissioning
• Cost Effective Access to information - Through standard RS232 & RS485 serial ports, and optional Ethernet and DeviceNet Ports
• Field upgradable firmware and settings
• Optional Conformal coating for exposure to chemically corrosive or humid environments

APPLICATIONS

• Protection and Management of three phase medium and large horsepower motors and driven equipment, including high inertia, two speed and reduced-voltage start motors.

FEATURES

Protection and Control
• Thermal model biased with RTD and negative sequence current feedback
• Start supervision and inhibit
• Mechanical jam
• Voltage compensated acceleration
• Undervoltage, overvoltage
• Underfrequency
• Stator differential protection
• Thermal overload
• Overtemperature protection
• Phase and ground overcurrent
• Current unbalance
• Power elements
• Torque protection
• Dual overload curves for 2 speed motors
• Reduced voltage starting control

Communications
• Multiple Ports - 10baseT Ethernet, RS485, RS232, RS422, DeviceNet
• Multiple Protocols - Modbus RTU, Modbus TCP/IP, DeviceNet

Monitoring and Metering
• A, V, W, var, VA, PF, Hz, Wh, varh, demand
• Torque, temperature (12 RTDs)
• Event recorder
• Oscillography & Data Logger (trending)
• Statistical information & learned motor data

EnerVistaTM Software
• State of the art software for configuration and commissioning GE Multilin products
• Document and software archiving toolset to ensure reference material and device utilities are up-to-date
• EnerVista™ Integrator providing easy integration of data in the 469 into new or existing monitoring and control systems
Protection and Control

The 469 is a digital motor protection system designed to protect and manage medium and large motors and driven equipment. It contains a full range of selectively enabled, self-contained protection and control elements as detailed in the Functional Block Diagram and Features table.

Motor Thermal Model

The primary protective function of the 469 is the thermal model with six key elements:

- Overload Curves
- Unbalance Biasing
- Hot/Cold Safe Stall Ratio
- Motor Cooling Time Constants
- Start Inhibit and Emergency Restart
- RTD Biasing

Overload Curves

The curves can take one of three formats: standard, custom, or voltage dependent. For all curve styles, the 469 retains thermal memory in a thermal capacity used register which is updated every 0.1 second. The overload pickup determines where the running overload curve begins.

The 469 standard overload curves are of standard shape with a multiplier value of 1 to 15.

The voltage dependent overload curves are used in high inertia load applications, where motor acceleration time can actually exceed the safe stall time and motor thermal limits. During motor acceleration, the programmed thermal overload curve is dynamically adjusted with reference to the system voltage level. The selection of the overload curve type and the shape is based on motor thermal limit curves provided by motor vendor.
Unbalance (Negative Sequence Current) Biasing

Negative sequence current, which causes rotor heating, is not accounted for in the thermal limit curves supplied by the motor manufacturer. The 469 measures unbalance as the ratio of negative to positive sequence current. The thermal model is biased to reflect the additional heating. Motor derating due to current unbalance can be selected via the setpoint unbalance bias k factor. Unbalance voltage causes approximately 6 times higher level of current unbalance (1% of voltage unbalance equal to 6% of current unbalance). Note that the k=8 curve is almost identical to the NEMA derating curve.

Hot/Cold Safe Stall Ratio

The Hot/Cold Safe Stall time ratio defines the steady state level of thermal capacity used (TCU) by the motor. This level corresponds to normal operating temperature of the fully loaded motor and will be adjusted proportionally if motor load is lower then rated. The Hot/Cold Safe Stall ratio is used by the relay to determine the lower limit of the running cool down curve, and also defines the thermal capacity level of the central point in RTD Biasing curve.

Start Inhibit and Emergency Restart

The Start Inhibit function prevents starting of a motor when insufficient thermal capacity is available or motor start supervision function dictate the start inhibit. In case of emergency the thermal capacity used and motor start supervision timers can be reset to allow the hot motor starting.

RTD Biasing

The 469 thermal overload curves are based solely on measured current, assuming a normal 40°C ambient and normal motor cooling. The actual motor temperature will increase due to unusually high ambient temperature, or motor cooling blockage. Use the RTD bias feature to augment the thermal model calculation of Thermal Capacity Used, if the motor stator has embedded RTDs. The RTD bias feature is feedback of measured stator temperature. This feedback acts to correct the assumed thermal model. Since RTDs have a relatively slow response, RTD biasing is useful for slow motor heating. Other portions of the thermal model are required during starting and heavy overload conditions when motor heating is relatively fast.

For RTD temperatures below the RTD BIAS MINIMUM setting, no biasing occurs. For maximum stator RTD temperatures above the RTD BIAS MAXIMUM setting, the thermal memory is fully biased and forced to 100%. At values in between, if the RTD bias thermal capacity used is higher compared to the thermal capacity used created by other features of the thermal model, then this value is used from that point onward.

Motor Start Supervision

Motor Start Supervision consists of the following features: Time-Between-Starts, Start-per-Hour, Restart Time. These elements are intended to guard the motor against excessive starting duty, which is normally defined by the motor manufacturer in addition to the thermal damage curves.

Mechanical Jam and acceleration time

These two elements are used to prevent motor damage during abnormal operational conditions such as excessively long acceleration times or stalled rotor.

Phase Differential Protection

This function is intended to protect the stator windings and supply power cables of large motors. Two types of current transformers connections are supported:

- 6 CT’s externally connected in the summing configuration.
- 3 Flux Balancing CT’s.

Separate trip pickup levels and time delays are provided for motor starting and running conditions.

Short Circuit Trip

This function is intended to protect the stator windings of the motors against phase-to-phase faults. Equipped with an overreach filter, the
469 removes the DC component from the asymmetrical current present at the moment a fault occurs or motor starts. A trip backup feature is also available as part of this function, used to issue a second trip if the fault is not cleared within a given time delay. The backup feature can also be assigned to an auxiliary contact for annunciation or remote tripping of upstream protection devices.

**Ground Fault**
This function is designed to protect motors against phase to ground faults. There are two dedicated ground current inputs in the relay, which support the following types of ground current detection.

- Core balance (Zero sequence) current transformer.
- Core balance (Zero sequence) 50:0.025 A (sensitive) current transformer.
- Residual connection of phase current transformers.

The function is equipped with an overreach filter, which removes the DC component from the asymmetrical current present at the moment a fault occurs, or a motor starts. Two pickup levels (trip and alarm) with individual time delays are available for ground fault detection. A trip Backup feature is also available as part of this function. The operational principal of Ground Fault Trip Backup is the same as of Short Circuit Trip Backup.

**Voltage and Frequency Protection**
Use the voltage and frequency protection functions to detect abnormal system voltage and frequency conditions, potentially hazardous to the motor. The following voltage elements are available:

- Over and Undervoltage
- Over and Underfrequency
- Phase Reversal

To avoid nuisance trips, the 469 can be set to block the undervoltage element when the bus that supplies power to the motor is de-energized, or under VT fuse failure conditions.

**Power Elements**
The following power elements are available in 469 relay. The first four elements have blocking provision during motor starting.

**Power Factor**
This element is used in synchronous motors applications to detect out-of-synchronism conditions.

**Reactive Power**
This element is used in applications where the reactive power limit is specified.

**Underpower**
Used to detect loss of load.

**Reverse Active Power**
Useful to detect conditions where the motor can become a generator.

**Overtorque**
This element is used to protect the driven load from mechanical breakage.

**Current Unbalance**
In addition to thermal model biasing current unbalance is available in the 469 relay as an independent element with 2 pickup levels and a built-in single phasing detection algorithm.

**RTD Protection**
The 469 has 12 programmable RTD inputs supporting 4 different types of RTD sensors. RTD inputs are normally used for monitoring stator, bearings, ambient temperature as well as other parts of the motor assembly that can be exposed to overheating. Each RTD input has 3 operational levels: alarm, high alarm and trip. The 469 also supports RTD trip voting and provides open/short RTD failure alarms.

**Additional and Special Features**
- Two speed motor protection.
- Load averaging filter for cyclic load applications
- Reduced voltage starting supervision.
- Variable frequency filter allowing accurate sensing and calculation of the analog values in VFD applications.
- Analog input differential calculation for dual drives applications.
- Speed counter trip and alarm.
- Universal digital counter trip and alarm.
- Pulsing KWh and Kvarh output.
- Trip coil supervision.
- Drawout indicator, Setpoints Access and Test permit inputs.
- Undervoltage Autorestart [Optional]
- Broken rotor bar detection system [Optional]
- VT Fuse Failure

**Inputs and Outputs**

**Current and Voltage Inputs**
The 469 has two sets of three phase CT inputs, one for phase current, and one dedicated for differential protection. The ratings of the phase current inputs (1A and 5A) must be specified when ordering the relay, while the ratings for differential inputs are field programmable, supporting both 1A and 5A secondary currents. There are also 2 single-phase ground CT inputs: A standard input with settable secondary rating; 5A or 1A, and a high sensitivity ground current detection input for high resistance grounded systems. Three phase VT inputs support delta and wye configuration and provide voltage signals for all voltage, frequency and power based protection elements and metering.

**Digital Inputs**
The 469 has 5 predefined inputs:

- Starter Status
- Emergency Restart
- Remote Reset
- Setpoint Access
- Test Switch

The 469 also has four assignable digital inputs, which can be configured as the following functions:
• Remote Trip and Alarm
• Speed Switch Trip and Tachometer
• Vibration Switch Trip and Alarm
• Pressure Switch Trip and Alarm
• Load Shed Trip
• Universal Digital Counter
• External oscillography trigger and External Relay Fault Simulation initiation
• General Switch with programmable functions and outputs

**Analog Inputs and Outputs**

Use the four configurable analog inputs available in the 469 to measure motor operation related quantities fed to the relay from standard transducers. Each input can be individually set to measure 4-20 mA, 0-20 mA or 0-1 mA transducer signals. The 469 can also be set to issue trip or alarm commands based on signal thresholds.

Use the four configurable analog outputs available in the 469 to provide standard transducer signals to local monitoring equipment. The desired output signal must be specified when the relay is ordered, either 4-20 mA, or 0-1 mA. The analog outputs can be configured to provide outputs based on any measured analog value, or any calculated quantity.

**Output Relays**

There are six Form-C output relays available in the 469. Four relays are always non-failsafe and can be selectively assigned to perform trip, or alarm functions. A non-failsafe block start relay is also provided, controlled by protection functions requiring blocking functionality. Loss of control power or 469 internal failures are indicated via the failsafe service relay. The trip and alarm relays can also be configured with latching functionality.

**Monitoring and Metering**

The 469 includes high accuracy metering and recording for all AC signals. Voltage, current, RTD and power metering are built into the relay as a standard feature.

**Metering**

The following system values are accurately metered and displayed:

- Phase, differential and ground currents, average current, motor load, current unbalance.

- Phase-to-ground and Phase-to-phase voltages, average phase voltage, system frequency.
- Real, reactive, apparent power, power factor, watthours, varhours, torque
- Current and power demand.
- Analog inputs and RTD temperatures.
- Thermal capacity used, lockout times, motor speed

**Monitoring**

The 469 is equipped with monitoring tools to capture data. The following information is presented in a suitable format.

- Status of inputs, outputs and alarms
- Last trip data
- Motor learned parameters: last and maximum acceleration times, starting currents and starting TCU, average currents, RTD maximums, analog inputs maximums and minimums.
- Trip and general counters, motor running hours and start timers.
- Event recorder
- Oscillography

**Event Recorder**

The event recorder stores motor and system information with a date and time

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**User Interface**

- **469 STATUS INDICATORS**
  - 469 status
  - Motor status
  - Output relays

- **NUMERIC KEYPAD**
  Numeric keys allow for simple entry of setpoint values. Control keys allow simple navigation through setpoint and actual value message structures. Help key provides context sensitive help messages

- **VALUE KEYS**
  Value Up, and Value Down keys to change setpoint values

- **PROGRAM PORT INTERFACE**
  RS-232 for connection to a computer, 9600 baud Programmable baud rate up to 19200

- **LARGE DISPLAY**
  Forty character display for viewing setpoints and actual value messages. Diagnostic messages are displayed when there is a trip or alarm condition. Default messages are displayed after a period of inactivity.

- **CONTROL AND PROGRAMMING KEYS**
  Menu, Escape, Reset, Enter, Menu Up, and Menu Down keys for complete access without a computer

- **DRAWOUT HANDLE**
  With provision for a wire lead seal to prevent unauthorized removal
Motor Protection System

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User Interfaces

Keypad and Display
The 469 has a keypad and 40 character display for local monitoring and relay configuration without the need for a computer. Up to 20 user-selected default messages can be displayed when inactive. In the event of a trip, alarm, or start block, the display will automatically default to the pertinent message and the Message LED indicator will flash.

LED Indicators
The 469 has 22 LED indicators on the front panel. These give a quick indication of 469 status, motor status, and output relay status.

Communications
The 469 is equipped with three standard serial communications ports, one RS232 located in the front panel for easy troubleshooting and programming, and two RS485 in the rear of the relay. Optional 10BaseT Ethernet and DeviceNet ports are also available. The rear RS485 ports provide remote communications or connection to a DCS, SCADA, or PLC. The RS232 and RS485 ports support user programmable baud rates from 300 to 19,200 bps. The optional Ethernet port can be used to connect the 469 to 10 Mbps Ethernet networks. The three serial ports support ModBus® RTU protocol, while the Ethernet port supports ModBus® RTU via TCP/IP protocol. The communication system of the 469 is designed to allow simultaneous communication via all ports.

Using Ethernet as the physical media to integrate the 469 to Local or Wide Area Networks, replaces a multidrop-wired network (e.g., serial Modbus®), and eliminates expensive leased or dial-up connections, reducing monthly operating costs.

Oscillography
The 469 records up to 64 cycles with 12 samples per cycle of waveform data for 10 waveforms (Ia, Ib, Ic, Ig, Diffa, Diffb, Diffc, Va, Vb, Vc) each time a trip occurs. The record is date and time stamped.

Advanced Motor Diagnostics
The Multilin M60 provides advanced motor diagnostics including a broken rotor bar detection function. The broken rotor bar detection is a condition maintenance function that continuously monitors the motor’s health while in operation. The advanced Motor Current Signature Analysis (MCSA) continuously analyzes the motor current signature and based on preset algorithms will determine when a broken rotor bar is present in the motor. With fully programmable alarms, the broken rotor bar function will provide early detection of any rotor problems and advise maintenance personnel of the impending issue allowing for predictive maintenance of the motor and prevention of catastrophic motor failures.

By providing early indication of potential rotor problems, serious system issues such as: reduced starting torque, overloads, torque and speed oscillation and bearing wear can be avoided. With the advanced broken rotor bar detection system, advanced warning of impending problems reduces catastrophic failures, maximizing motor life and system uptime.

Simulation
The simulation feature tests the functionality and relay response to programmed conditions without the need for external inputs. When placed in simulation mode the 469 suspends reading of the actual inputs and substitutes them with the simulated values. Pre-trip and fault conditions can be simulated, with currents, voltages, system frequency, RTD temperatures, and analog inputs configured for each state.

Viewpoint Monitoring
Viewpoint Monitoring is a powerful yet simple-to-use monitoring and data recording of small systems. Viewpoint Monitoring provides a complete HMI package with the following functionality:

- Plug- &-Play Device Monitoring
- Single-Line Monitoring & Control
- Annunciator Alarming
- Trending Reports
- Automatic Event Retrieval
- Automatic Waveform Retrieval

EnerVista™ Integrator
EnerVista™ Integrator is a toolkit that allows seamless integration of GE Multilin devices into new or existing automation systems. Included in EnerVista Integrator is:

- OPC/DDE Server
- GE Multilin Drivers
- Automatic Event Retrieval
- Automatic Waveform Retrieval

EnerVista™ Software
The EnerVista™ Suite is an industry leading set of software programs that will simplify every aspect of using the 469 relay. Tools to monitor the status of your motor, maintain your relay, and integrate information measured by the 469 into HMI or SCADA monitoring systems are available. Also provided are the utilities to analyze the cause of faults and system disturbances using the powerful Waveform and Sequence of Event viewers that come with the 469 Setup Software that is included with each relay.

Viewpoint Maintenance
Viewpoint Maintenance provides tools that will increase the security of your 469, create reports on the operating status of the relay, and simplify the steps to troubleshoot protected generators. Tools available in Viewpoint Maintenance include:

- Settings Audit Trail Report
- Device Health Report
- Comprehensive Fault Diagnostics

EnerVista Software
EnerVista is a suite of software programs that will simplify every aspect of using the 469 relay. Tools to monitor the status of your motor, maintain your relay, and integrate information measured by the 469 into HMI or SCADA monitoring systems are available. Also provided are the utilities to analyze the cause of faults and system disturbances using the powerful Waveform and Sequence of Event viewers that come with the 469 Setup Software that is included with each relay.
Create complete settings files for your SR469 in 6 simple steps using the Motor Settings Auto-Configurator.

Typical Wiring
**Technical Specifications**

**PROTECTION**

**SINGLE PHASE CIRCUIT**

- **Pickup Level:** 2.0 to 2.0 x CT primary in steps of 0.1 for any one phase
- **Time Delay:** 0 to 1000 ms in steps of 10
- **Pickup Accuracy:** as per phase current inputs
- **Timing Accuracy:** ±0.5 s or ±0.5% of total time
- **Elements:** Trip

**REDUCED VOLTAGE START**

- **Transition Level:** 25 to 300% FLA in steps of 1
- **Transition Time:** 1 to 250 s in steps of 1
- **Transition Control:** Current, Timer, Current and Timer

**OVERLOAD/STALL PROTECTION/ THERMAL MODEL**

- **Overload Curves:** 15 standard overload curves, custom curve, voltage dependent, current curve for high inertia
- **Curve Biasing:** Phase unbalance
- **Max. per lead for Pt and Ni:**
  - ±100 ms or ±0.5% of total time

**DIGITAL INPUTS**

- **REMOTE SWITCH**
  - **Configurable:** Assignable to digital inputs 1 to 4
  - **Timing Accuracy:** 100 ms max.
  - **Elements:** Trip and Alarm

**OVERLOAD**

- **Pickup Level:** 1.01 to 1.10 x rated in steps of 0.01 for any one phase
- **Time Delay:** 0.1 to 60 x FLA in steps of 0.01
- **Pickup Accuracy:** as per voltage inputs
- **Timing Accuracy:** ±0.5 s or ±0.5% of total time
- **Elements:** Trip and Alarm

**VOLTAGE PHASE REVERSAL**

- **Configuration:** ABC or ACB phase rotation
- **Timing Accuracy:** 500 to 700 ms
- **Elements:** Trip

**FREQUENCY**

- **Required Voltage Pkg:** ≥ 30% of full scale in Phase A
- **Underfrequency Pkg:** 20.01 to 60.00 in steps of 0.01
- **Accuracy:** ±0.02 Hz

**UNBALANCE**

- **Unbalance:** ±2°C

**GROUND INSTANTANEOUS**

- **Pickup Level:** 0.05 to 1 x CT primary in steps of 0.01 for any one phase
- **Time Delay:** 0 to 100 ms in steps of 10
- **Pickup Accuracy:** as per phase current inputs
- **Timing Accuracy:** ±0.5 s or ±0.5% of total time
- **Elements:** Trip and Alarm

**PHASE DIFFERENTIAL**

- **Pickup Level:** 0.05 to 1 x CT primary in steps of 0.01 for any one phase
- **Time Delay:** 0 to 1000 ms in steps of 10
- **Pickup Accuracy:** as per phase differential current inputs
- **Timing Accuracy:** ±0.5 s or ±0.5% of total time
- **Elements:** Trip and Alarm

**GROUND INSTANTANEOUS**

- **Pickup Level:** 0.1 to 1 x CT primary in steps of 0.01 for any one phase
- **Time Delay:** 1 to 250.0 s in steps of 1
- **Pickup Accuracy:** as per ground current input
- **Timing Accuracy:** ±0.5 s or ±0.5% of total time
- **Elements:** Trip and Alarm

**INTERCURRENT**

- **Pickup Level:** 0.01 to 0.99 x CT
- **Time Delay:** 0.01 to 0.95 x CT alarm in steps of 0.01
- **Pickup Accuracy:** as per phase current inputs
- **Timing Accuracy:** ±0.5 s or ±0.5% of total time
- **Elements:** Trip and Alarm

**CURRENT UNBALANCE**

- **Unbalance:** ±2°C
- **Range:** ±1 to 2.5 for (service factor)

**INPUTS**

- **Trip and Alarm**
  - **Input Type:** Assignable to digital inputs 1 to 4
  - **Accuracy:** ±0.125 A for 50:0.025 at 25 A
  - **Response Time:** ±1 second at 80 x rated current

**VOLTAGE INPUTS**

- **VT Ratio:** 1.00 to 15.00:1 in steps of 0.01
- **Nominal Frequency:** 50 - 70 Hz
- **Frequency Range:** 20 - 120 Hz
- **Accuracy:** ±0.05 of % CT for 5 A
- **Continuous Range:** ≥ 1000
- **Maximum Continuous:** 280 V AC
- **Burden:** > 50 kVA

**INTERCURRENT**

- **Pickup Level:** 1.0 to 5000 A
- **Time Delay:** 0.05 to 10000 s in steps of 0.1
- **Pickup Accuracy:** as per voltage inputs
- **Timing Accuracy:** ±2% of total time
- **Elements:** Trip and Alarm

**DIGITAL INPUTS**

- **SENSING**
  - **RTD:** ±2°C
  - **Shunt/Line Alarms:** < -50°C
  - **TRIP COIL SUPERVISION**
  - **Applicable Voltage:** 20 to 300 V DC / V AC
  - **Trickle Current:** 2 to 5 mA

**ANALOG INPUTS**

- **Current Inputs:** 0 to 1 mA, 0 to 20 mA or 4 to 20 mA
- **Input Impedance:** 220 kΩ ±10%
- **Conversion Range:** 0 to 21 mA
- **Accuracy:** ±1% of full scale
- **Type:** Analog In Supply: +24 V DC at 10 mA maximum
- **Response Time:** ≤ 100 ms
Technical Specifications (continued)

**MONITORING**

**POWER FACTOR**
- Range: 0.01 lead or lag to 1.00
- Time Delay: 0.90 to 0.05 in steps of 0.91
- Pickup Accuracy: ±0.02
- Timing Accuracy: ±0.005 ms or ±0.5% of total time
- Elements: Trip and Alarm

**3-PHASE REAL POWER**
- Range: 0 to 65535 kVA at Iavg = 2 x CT: ±1% of 3 x 2 x CT x VT x VT full scale at Iavg > 2 x CT±1.5% of 3 x 20 x CT x VT x VT full scale
- Time Delay: ±0.5 s or ±0.5% of total time
- Elements: Trip and Alarm

**3-PHASE APPARENT POWER**
- Range: 0 to a99999 kW
- Pickup Level: ±1 to 25000 kW in steps of 1
- Block From Start: ±0 to 15000 s in steps of 1
- Pickup Accuracy: ±0.02
- Timing Accuracy: ±0.05 s or ±0.5% of total time
- Elements: Trip and Alarm

**3-PHASE REACTIVE POWER**
- Range: 0 to a99999 kVAr
- Pickup Level: ±1 to 25000 kW in steps of 1
- Block From Start: ±0 to 15000 s in steps of 1
- Pickup Accuracy: ±0.02
- Timing Accuracy: ±0.05 s or ±0.5% of total time
- Elements: Trip and Alarm

**POWER SUPPLY**

**CONTROL POWER**
- Options: LO / HI (must be specified with order)
- LO Range: DC 20 to 60 V DC, AC 20 to 48 V
- Hi Range: DC 48 to 60 V DC, AC 48 to 62 Hz
- Power: 45 VA (max), 25 VA typical
- Proper operation time without supply voltage: 30 ms

**COMMUNICATIONS**
- RS232 Port: 1. Front Panel, non-isolated
- RS485 Ports: 2. Isolated together at 36 vpk
- Baud Rates: RS485: 300 - 19,200 Baud
- Parity: None, Odd, Even
- Protocol: Modbus® RTU / half duplex
- Ethernet Port: 10BaseT, RJ45 Connector, DeviceNet®

**PRODUCT TESTS**

**Thermal Cycling:** Operational test at ambient, reducing to –40°C and then increasing to 60°C
**Dielectric Strength:** 2.0 kV for 1 minute from relay, Cts, Vts, power supply to Safety Ground

**ENVIRONMENTAL**

**Temperature Range:** Operating: –40°C to +60°C
**Ambient Storage:** –40°C to +80°C
**Ambient Shipping:** –40°C to +80°C
**Humidity:** Operating up to 95% non-condensing @ 55°C
**Pollution Degree:** 2
**IP Rating:** IP40 (front), IP20 (back)
## Ordering

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<th>P5</th>
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<th>Basic Unit</th>
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<td>469 Motor Protection System</td>
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<td>5 A phase CT secondaries</td>
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<td>Enhanced front panel with Ethernet 10BaseT option</td>
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<td>Harsh (Chemical) Environment Conformal Coating</td>
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### Accessories for the 469:
- 469 Motor Protection Learning CD: TRCD-469-C-S-1
- Multilink Ethernet Switch: ML2400-F-HI-HI-A2-A2-A6-G1
- Product Maintenance Learning CD: TRCD-MAINT-C-S-1
- Viewpoint Maintenance: VPM-1
- Viewpoint Monitoring: VP-1

### Visit www.GEMultilin.com/469 to:
- View Guideform Specifications
- Download the instruction manual
- Review applications notes and support documents
- Buy a 469 online